## Can-Stack Actuators

The Haydon<sup>TM</sup> brand of can-stack stepper motor linear actuators provides both a broader range and, for a given size, significantly higher thrust than previously available from mini-steppers, Haydon Kerk Motion Solutions patented design accepts a larger rotor than conventional units, improving efficiency and eliminating the need for massive heat sinks. Unique features impart ruggedness and reliability that assure long life and consistent performance. Rare earth magnets are available for even higher thrust. All units are built with dual ball bearings for greater motion control, precise step accuracy and long life.

#### G4 19000 Series • Can-Stack Stepper Motor Linear Actuators

G4 19000 Series Ø 20 mm (.79-in) Can-Stack Stepper Motor Linear Actuators

Utilizing high energy rare earth (neodymium) magnets,the G4 Series linear actuators consistently deliver exceptional performance. All units are built with dual ball bearings.

The highest force of any similar size linear actuator stepper motor

#### Multiple versions available

- Captive
- Non-Captive
- External Linear



Ø20mm (.79-in)

#### Specifications

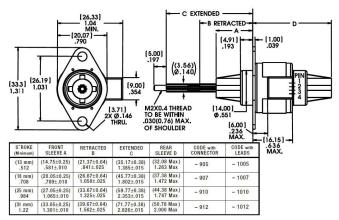
0 20 mm (.79-in) Motor						
Captive		1944 –	_ †	1954 -	_ †	
Part No.	Non-Captive	1934 -	_ †	1984 –	_ †	
	External Linear*	E1944 –	_ †	E1954 –		
ı	Wiring Bipolar					
Step angle		7.5°		15°		
Winding Voltage		5 VDC	12 VDC	5 VDC	12 VDC	
Current (RMS)/phase		350 mA	160 mA	338 mA	140 mA	
Resist	ance/phase	14.0 Ω	74.5 Ω	14.8 Ω	85.5 Ω	
Induct	ance/phase	6.24 mH 31.2 mH 6.84 mH			37.8 mH	
Power (	Consumption	3,38 W				
Insul	ation Class	Class B				
١	Weight	1.24 oz (35 g)				
Insulatio	on Resistance		20	MΩ		

Lir	Order Code I.D.		
step	inches mm		oode i.b.
	0.0005	0.013	3
7.5° Angle	0.001	0.0254	1
7 tilgio	0.002	0.051	2
	0.001	0.0254	1
15° Ana <b>l</b> e	0.002	0.051	2
7910	0.004	0.102	4

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

#### Captive Lead Screw

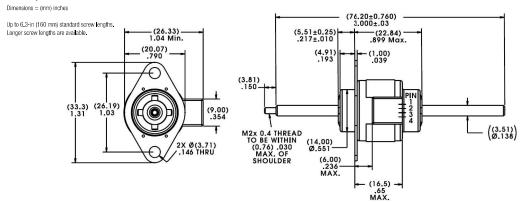
Dimensions = (mm) inches



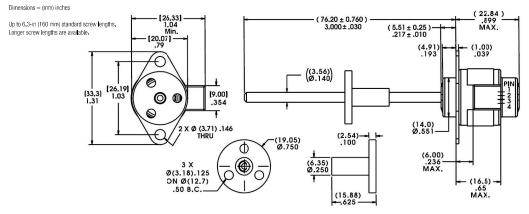
<sup>\*</sup>Part numbering information on page 147.

#### G4 19000 Series • Can-Stack Stepper Motor Linear Actuators

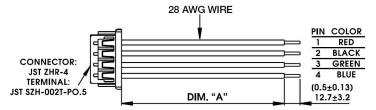
#### Non-Captive Lead Screw



#### **External Linear**



#### Connector



Part Number	Dimension "A"
56-1318-4	(24 ±0.39) 610 ±10 mm
56-1318-3	(18 ±0.39) 450 ±10 mm
56-1318-2	(12 ±0.39) 305 ±10 mm
56-1318-1	(6 ±0.39) 150 ±10 mm

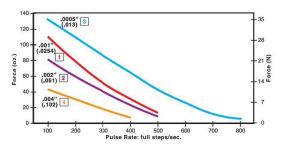


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#### ☐ G4 19000 Series • Can-Stack Stepper Motor Linear Actuators

#### FORCE vs. PULSE RATE

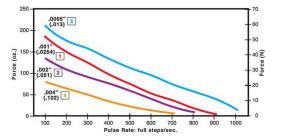
- L/R Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

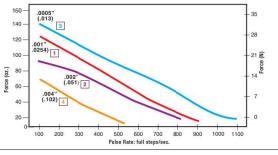
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



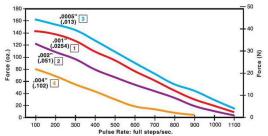
#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

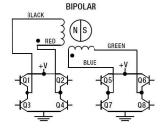
#### G4 19000 Series • Can-Stack Stepper Motor Linear Actuators

#### Identifying the Can-Stack Number Codes when Ordering

Е	19	5	4	2	05	1005
Prefix (include only when using the following)  E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 19 = 19000 (Series numbers represent approximate diameters of motor body)	Style 3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External version) 5 = 15° Captive or External (use "E" or "K" Prefix for External version 8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -1005 = captive 13mm stroke with leads -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

#### Can-Stacks: Wiring



#### Can-Stacks: Stepping Sequence

	Bipolar	Q2 <b>-</b> Q3	Q1 <b>-</b> Q4	Q6 <b>-</b> Q7	Q5-Q8	
贝	Step					<b>A</b>
EXTEND CW	1	ON	0FF	ON	OFF	
CW-	2	OFF	ON	ON	0FF	RETRACT CCW
	3	OFF	ON	OFF	ON	PACT
•	4	ON	0FF	0FF	ON	Æ
	1	ON	OFF	ON	OFF	

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

#### Can-Stack Stepper Motor Linear Actuators Options

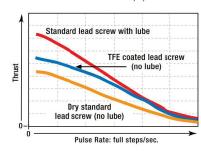
## TFE Coated Lead Screws for applications that require a permanent, dry lubricant

Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a "dry" stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external linear. Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.

#### Lead Screw Comparison: FORCE vs. PULSE RATE

- L/R Drive - 100% Duty Cycle



## Home Position Switch monitors movements more precisely for greater control and improved quality control

Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions, Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available.

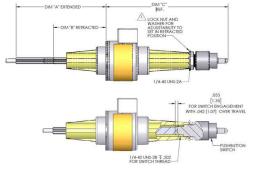
Activation force of 10 oz (2.78 N) required therefore may not be appropriate for

smaller can-stack actuators.

When ordering motors with the home position switch, the part number should be preceded by an "S".

Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 milliohms typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	1







Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)	Dim "C" Ref. inches (mm)
.512 (13)	1.385 +/015 (35.17 +/- 0.38)	.841 +/025 (21.37 +/- 0.64)	2.230 +/025 (56.63 +/- 0.64)
.708 (18)	1.802 +/015 (45.77 +/- 0.38)	1.050 +/025 (26.67 +/- 0.64)	2.438 +/025 (61.93 +/- 0.64)
.984 (25)	2.353 +/015 (59.77 +/- 0.38)	1.325 +/025 (33.67 +/- 0.64)	2.714 +/025 (68.93 +/- 0.64)
1.22 (31)	N.	ce	





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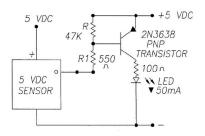


#### ■ Can-Stack Stepper Motor Linear Actuators Options

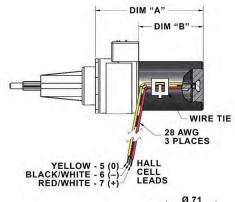
End of Stroke Proximity Sensor incorporates a hall effect device, activated by a rare earth magnet embedded in the end of the internal screw

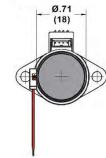
Compact profile of the sensor allows for installation in limited space applications. Virtually unlimited cycle life. Special cabling and connectors available.

Specificati	ons		
Supply Voltage (VDC)		3.8 min. to 24 max.	
Current Co	onsumption	10 mA max.	
Output Voltage (operated)		0.15 typ., 0.40 max. Sinking 20 mA max.	
Output Current		20 mA max.	
Output Leak (rele	kage Current ased)	10µA max. @ Vout = 24 VDC; Vcc = 24 VDC	
Output Switching	Rise, 10 to 90%	.05 μs typ., 1.5 μs max. @ Vcc = 12 V, RL = 1.6 K0hm	
Time	Fall, 90 to 10%	.15 μs typ., 1.5 μs max. @ CL = 20 pF	
Temperature		− 40 to +150°C	



NOTE: Sensor is category 2 ESD sensitive per DOD-STD-1686A. Assembly operations should be performed at workstations with conductive tops and operators grounded.





Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)
.512 (13)	1.360 (34.55)	.73 (18.55)
.708 (18)	1.569 (39.85)	.94 (23.85)
.984 (25)	1.844 (46.85)	1.21 (30.85)
1.22 (31)	2.081 (52.85)	1.45 (36.85)

The sensor has virtually unlimited cycle life, Special cabling and connectors can also be provided,

## G4 25000 Series Ø 25 mm (1.0-in) Can-Stack Stepper Motor Linear Actuators

High durability and exceptional performance.
All units are built with dual ball bearings.

Generates higher force than other competitors

#### Multiple versions available

- Captive
- Non-Captive
- External Linear



### Specifications

Ø 25 mm (1.0-in) Motor						
Captive		2544 – – †		2554 – – †		
Part No.	Non-Captive	2534 -	- †	2584 -	†	
	External Linear*	E2544 -	†	E2554 -		
1	Wiring		Bip	o <b>l</b> ar		
Sto	ep angle	7.5°		15°		
Winding Voltage		5 VDC	12 VDC	5 VDC	12 VDC	
Current (RMS)/phase		385 mA	160 mA	385 mA	160 mA	
Resistance/phase		13 Ω	72 <b>Ω</b>	13 Ω	72 <b>Ω</b>	
Induct	ance/phase	10.8 mH	60 mH	8.08 mH	48 mH	
Power	Consumption	3.85 W				
Rot	or Inertia		1.07	gcm <sup>2</sup>		
Insul	ation Class	Class B				
1	Weight	1.74 oz (49 g)				
Insulatio	on Resistance		20	MΩ		

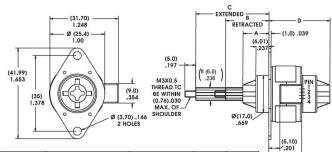
	Linear Travel / Step 15° Step Angle						
step	inches mm		Code I.D.				
7.50	0.0005	0.013	3				
7.5° Anale	0.001	0.0254	1				
raigio	0.002	0.051	2				
	0.001	0.0254	1				
15° Ang <b>l</b> e	0.002	0.051	2				
, angle	0.004	0.102	4				

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

†Part numbering information on page 153.

#### Captive Lead Screw

Dimensions = (mm) inches



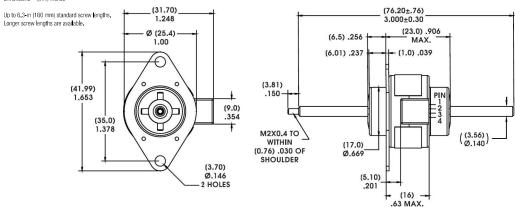
Stroke (Minimum) inches (mm)	Front Sleeve A inches (mm)	Retracted B inches (mm)	Extended C inches (mm)	Rear Sleeve D inches (mm)	Code with Connector	Code with Leads	(16) - .65 MAX.
.512 (13 mm)	472 +/010 (11.99 +/- 0.25)	.787 +/025 (19.99 +/- 0.64)	1.329 +/015 (33.76 +/- 0.38)	1.128 Max. (28.65 Max.)	- 905	- 1005	
.708 (18 mm)	680 +/010 (17.28 +/- 0.25)	.994 +/025 (25.25 +/- 0.64)	1.743 +/015 (44.27 +/- 0.38)	1.336 Max. (33.94 Max.)	- 907	- 1007	
.984 (25 mm)	955 +/010 (24.26 +/- 0.25)	1.269 +/025 (32.23 +/- 0.64)	2.293 +/015 (58.24 +/- 0.38)	1.611 Max. (40.92 Max.)	- 910	- 1010	
1,22 (31 mm)	1.191 +/010 (30.25 +/- 0.25)	1.505 +/025 (38.23 +/- 0.64)	2.765 +/015 (70.23 +/- 0.38)	1.847 Max. (46.91 Max.)	- 912	- 1012	



#### G4 25000 Series • Can-Stack Stepper Motor Linear Actuators

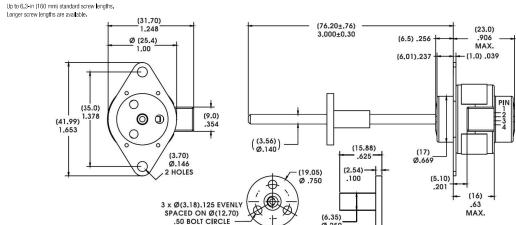
#### Non-Captive Lead Screw

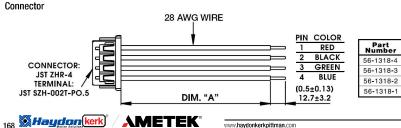
Dimensions = (mm) inches



#### **External Linear**

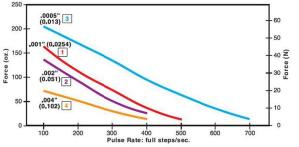
Dimensions = (mm) inches





#### FORCE vs. PULSE RATE

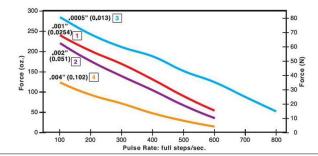
- L/R Drive
- Bipolar
- 100% Duty Cycle



☐ G4 25000 Series • Can-Stack Stepper Motor Linear Actuators

#### FORCE vs. PULSE RATE

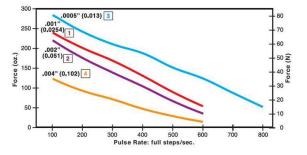
- L/R Drive
- Bipolar
- 25% Duty Cycle



#### FORCE vs. PULSE RATE

Obtained by a special winding or by running a standard motor at double the rated current.

- Chopper Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar

Dimension "A"

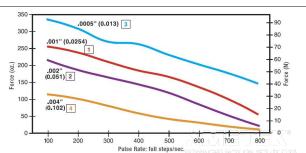
(24 ±0.39) 610 ±10 mm

(18 ±0.39) 450 ±10 mm

(12 ±0.39) 305 ±10 mm

(6 ±0.39) 150 ±10 mm

- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can in

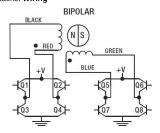
#### G4 25000 Series • Can-Stack Stepper Motor Linear Actuators

#### Identifying the Can-Stack Number Codes when Ordering

Е	25	5	4	4	12	1010
Prefix (include only when using the following)  E = External  K = External with 40° thread form  P = Proximity Sensor  S = Home Position Switch	Series Number Designation 25 = 25000 (Series numbers represent approximate diameters of motor body)	Style 3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External for	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -1010 = captive 25mm stroke with leads -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

#### Can-Stacks: Wiring



#### Can-Stacks: Stepping Sequence

Bipo <b>l</b> ar	Q2 <b>-</b> Q3	Q1-Q4	Q6 <b>-</b> Q7	Q5-Q8	] .
Step					1
1	ON	0FF	ON	OFF	
2	OFF	ON	ON	OFF	NOO IC
3	OFF	ON	OFF	ON	RETRACT
4	ON	0FF	OFF	ON	æ
1	ON	OFF	ON	OFF	
	Step 1 2	Step 1 ON 2 OFF 3 OFF 4 ON	Step         ON         OFF           1         ON         OFF           2         OFF         ON           3         OFF         ON           4         ON         OFF	Step         ON         OFF         ON           1         ON         OFF         ON           2         OFF         ON         ON           3         OFF         ON         OFF           4         ON         OFF         OFF	Step         ON         OFF         ON         OFF           1         ON         OFF         ON         OFF           2         OFF         ON         ON         OFF           3         OFF         ON         OFF         ON           4         ON         OFF         OFF         ON

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

#### ■ Can-Stack Stepper Motor Linear Actuators Options

#### TFE Coated Lead Screws for applications that require a permanent, dry lubricant

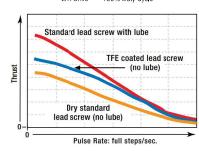
Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a "dry" stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external linear

Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.

#### Lead Screw Comparison: FORCE vs. PULSE RATE

- L/R Drive - 100% Duty Cycle



#### Home Position Switch monitors movements more precisely for greater control and improved quality control

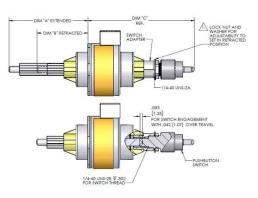
Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions. Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available.

Activation force of 10 oz (2.78 N) required therefore may not be appropriate for smaller can-stack actuators.

When ordering motors with the home position switch, the part number should be preceded by an "S".

Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 milliohms typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	1 3 Multiple contact options available.







Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)	Dim "C" Ref. inches (mm)
.512 (13)	1.329 +/025	.787 +/025	2.051 +/025
	(33.76 +/- 0.64)	(19.99 +/- 0.64)	(52.09 +/- 0.64)
.708 (18)	1.743 +/025	.994 +/025	2.258 +/025
	(44.27 +/- 0.64	(25.25 +/- 0.64)	(57.35 +/- 0.64)
.984 (25)	2.293 +/025	1.269 +/025	2.534 +/025
	(58.24 +/- 0.64)	(32.23 +/- 0.64)	(64.37 +/- 0.64)
1.22 (31)	2.765 +/025	1.505 +/025	2.770 +/025
	(70.23 +/- 0.64)	(38.23 +/- 0.64)	(70.37 +/- 0.64)









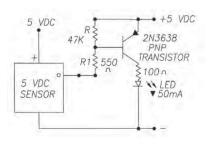
#### ■ G4 25000 Series • Can-Stack Stepper Motor Linear Actuators

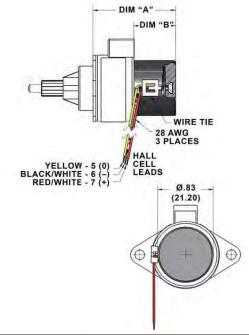
■ Can-Stack Stepper Motor Linear Actuators Options

End of Stroke Proximity Sensor incorporates a hall effect device, activated by a rare earth magnet embedded in the end of the internal screw

Compact profile of the sensor allows for installation in limited space applications. Virtually unlimited cycle life. Special cabling and connectors available.

Specificati	ons		
Supply Vol	tage (VDC)	3.8 min. to 24 max.	
Current Co	onsumption	10 mA max.	
Output Voltage (operated)		0.15 typ., 0.40 max. Sinking 20 mA max.	
Output Current		20 mA max.	
Output Leakage Current (released)		10µA max. @ Vout = 24 VDC; Vcc = 24 VDC	
Output Switching	Rise, 10 to 90%	.05 µs typ., 1.5 µs max. @ Vcc = 12 V, RL = 1.6 KOhm	
Time	Fall, 90 to 10%	.15 µs typ., 1.5 µs max. @ CL = 20 pF	
Tempe	erature	− 40 to +150°C	





Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)
.512 (13)	1.248 (31.71)	.632 (16.05)
.708 (18)	1.449 (36.81)	.833 (21.15)
.984 (25)	1.723 (43.76)	1.106 (28.10)
1.22 (31)	1.959 (49.76)	1.343 (34.10)

The sensor has virtually unlimited cycle life. Special cabling and connectors can also be provided.

#### G4 25000 Series E8T Encoder

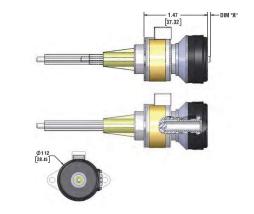
G4 25000 Series E8T Transmissive Optical Encoder is designed to provide the digital quadrature encoder feedback for high volume, compact space applications.

- Resolutions from 180 to 720
- Single-ended / Differential
- Frequency response to 100 kHz
- Low power consumption, 5 V @ 30 mA max
- · High retention polarized connector

#### Assembly Options:

- Differential line driver with complementary outputs
- Detachable cable
- Through-hole cover

— ITIIOUgii-ilole covei	
Stroke inches (mm)	Dim "A" Extended inches (mm)
.512 (13)	N/A
.708 (18)	N/A
.984 (25)	.071 (1.80)
1.22 (31)	.307 (7.80)





#### ☐ G4 37000 Series • Can-Stack Stepper Motor Linear Actuators

G4 37000 Series Ø 36 mm (1.4-in) Can-Stack Stepper Motor Linear Actuators

Outstanding durability and high performance. The G4 Series features high energy neodymium magnets and dual ball bearings.

Exceptionally high linear force-to-size ratio, ideal for precision motion

#### Multiple versions available

- Captive
- Non-Captive
- External Linear



#### Specifications

Specifications					
		Ø 36 mn	n (1.4-in) Motor		
	Captive	3744 –		3754 -	
Part No.	Non-Captive	3734 -	- 1	3784 -	†
	External Linear	E3744 -	_ †	E3754 -	- +
	Wiring		Bip	olar	
St	ep angle	7.5°		15°	
Winding Voltage		5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase		561 mA	230 mA	561 mA	230 mA
Resistance/phase		8.9 Ω	52 Ω	8.9 Ω	52 Ω
Induct	tance/phase	11.6 mH	65 mH	8.5 mH	46 mH
Power	Consumption		5.6	6 W	
Rot	or Inertia	8.5 gcm <sup>2</sup>			
Insul	ation Class	Class B			
1	Weight	4.2 oz (120 g)			
Insulation	on Resistance		20	MΩ	

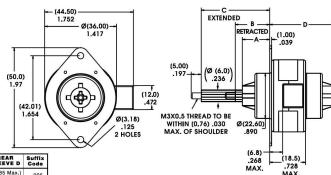
Lir	Order Code I.D.				
step	step inches mm				
7.5° Angle	0.0005	0.013	3		
	0.001	0.0254	1		
7 tilgio	0.002	0.051	2		
	0.001	0.0254	1		
15° Ang <b>l</b> e	0.002	0.051	2		
7 tilgjo	0.004	0.102	4		

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

\*Part numbering information on page 159.

#### Captive Lead Screw

Dimensions = (mm) inches



STROKE	FRONT	RETRACTED	EXTENDED	REAR	Suffix
(Minimum)	SLEEVE A	B	C	SLEEVE D	
(16.0 mm)	(13.67±0.25)	(17.19±0.64)	(34.24±0.38)	(33.85 Max.)	- 905
0,631	.538±.010	.677±,025	1,348±,015	1,333 Max.	
(25.4 mm)	(26.37±0.25)	(29.89±0.64)	(56.94±0.38)	(46.55 Max.)	- 910
1.00	1.038±.010	1.177±.025	2.348±.015	1.833 Max.	
(38.1 mm)	(39.07±0.25)	(42.59±0.64)	(85.04±0.38)	(59.25 Max.)	- 915
1.50	1.538±.010	1.677±.025	3.348±.015)	2.333 Max.	

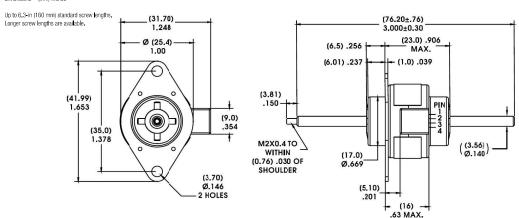




### G4 37000 Series • Can-Stack Stepper Motor Linear Actuators

#### Non-Captive Lead Screw

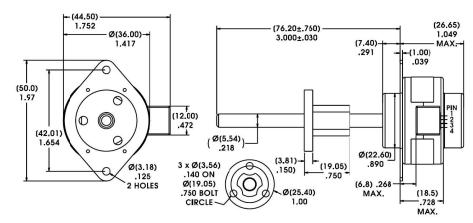
Dimensions = (mm) inches

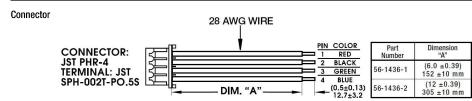


#### **External Linear**

Dimensions = (mm) inches

Up to 6.3-in (160 mm) standard screw lengths. Longer screw lengths are available.







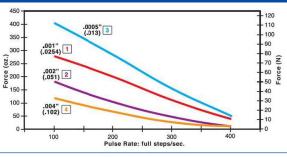


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#### ☐ G4 37000 Series • Can-Stack Stepper Motor Linear Actuators

#### FORCE vs. PULSE RATE

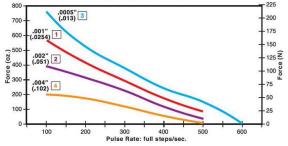
- L/R Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

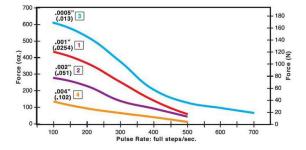
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



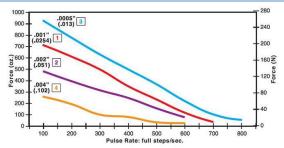
#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Actuator bearings are rated for 75 lbs.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stor the motor without overshoot.



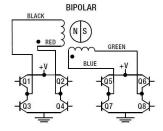


#### Identifying the Can-Stack Number Codes when Ordering

E	37	4	4	2	05	1015
Prefix (include only when using the following)  E = External K = External with 40° thread form P = Proximity Sensor S = Home Position Switch	Series Number Designation 37 = 37000 (Series numbers represent approximate diameters of motor body)	Style 3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External version) 5 = 15° Captive or External (use "E" or "K" Prefix for External version 8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -1015 = captive 38. Imm stroke with leads -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

#### Can-Stacks: Wiring



#### Can-Stacks: Stepping Sequence

	Bipo <b>l</b> ar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8	
贝	Step					<b>A</b>
EXTEND	1	ON	0FF	ON	OFF	
CW-	2	0FF	ON	ON	0FF	CCW
l	3	OFF	ON	OFF	ON	RETRACT
•	4	ON	0FF	0FF	ON	Æ
	1	ON	OFF	ON	OFF	

Note: Hallf stepping is accomplished by inserting an off state between transitioning phases.

#### Can-Stack Stepper Motor Linear Actuators Options

## TFE Coated Lead Screws for applications that require a permanent, dry lubricant

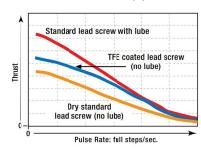
Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a "dry" stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external linear.

Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.

#### Lead Screw Comparison: FORCE vs. PULSE RATE

- L/R Drive - 100% Duty Cycle



## Home Position Switch monitors movements more precisely for greater control and improved quality control

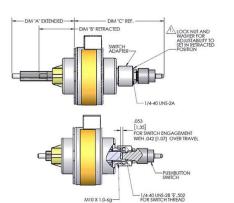
Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions. Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available.

Activation force of 10 oz (2.78 N) required therefore may not be appropriate for smaller can-stack actuators.

When ordering motors with the home position switch, the part number should be preceded by an "S".

Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 milliohms typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	1 3 Multiple contact options available.







Stroke inches (mm)	Dim "A" Extended inches (mm)	Dim "B" Retracted inches (mm)	Dim "C" Ref. inches (mm)
.631 (16)	1.348 +/025 (34.24 +/- 0.64)	.677 +/025 (17.19 +/- 0.64)	2.218 +/025 (56.33 +/- 0.64)
1.00 (25.4)	2.348 +/025 (56.94 +/- 0.64)	1.177 +/025 (29.89 +/- 0.64)	2.718 +/025 (69.03 +/- 0.64)
1.50 (38.1)	3.348 +/025 (85.04 +/- 0.64)	1.677 +/025 (42.59 +/- 0.64)	3.218 +/025 (81.73 +/- 0.64)



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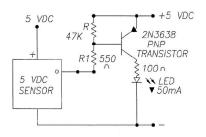
#### ☐ G4 37000 Series • Can-Stack Stepper Motor Linear Actuators

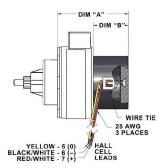
#### ■ Can-Stack Stepper Motor Linear Actuators Options

#### End of Stroke Proximity Sensor incorporates a hall effect device, activated by a rare earth magnet embedded in the end of the internal screw

Compact profile of the sensor allows for installation in limited space applications. Virtually unlimited cycle life. Special cabling and connectors available.

Specificati	ons		
Supply Vol	tage (VDC)	3,8 min, to 24 max,	
Current Consumption		10 mA max.	
Output Voltage (operated)		0.15 typ., 0.40 max. Sinking 20 mA max.	
Output Current		20 mA max.	
Output Leal (rele	kage Current ased)	10µA max, @ Vout = 24 VDC; Vcc = 24 VDC	
Output Switching	Rise, 10 to 90%	.05 µs typ., 1.5 µs max. @ Vcc = 12 V, RL = 1.6 K0hm	
Time	Fall, 90 to 10%	.15 μs typ., 1.5 μs max. @ CL = 20 pF	
Tempe	erature	- 40 to +150°C	







Stroke inches (mm)	Dim "A" inches (mm)	Dim "B" inches (mm)
.631 (16)	1.404 (35.65)	.695 (17.65)
1.00 (25.4)	1.906 (48.41)	1.197 (30.41)
1.50 (38.1)	2.409 (61.18)	1.700 (43.18

The sensor has virtually unlimited cycle life. Special cabling and connectors can also be provided.

#### G4 37000 Series E8T Encoder

G4 37000 Series E8T Transmissive Optical Encoder is designed to provide the digital quadrature encoder feedback for high volume, compact space applications.

- Resolutions from 180 to 720
- . Single-ended / Differential
- Frequency response to 100 kHz

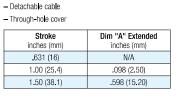
178 **Haydon kerk** 

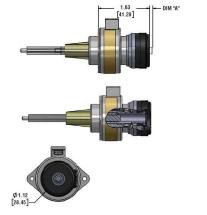
- Low power consumption, 5 V @ 30 mA max
- · High retention polarized connector

#### Assembly Options:

- Differential line driver with complementary outputs

Stroke inches (mm)	Dim "A" Extended inches (mm)
.631 (16)	N/A
1.00 (25.4)	.098 (2.50)
1.50 (38.1)	.598 (15.20)







## ■ 15000 Series • Can-Stack Stepper Motor Linear Actuators

15000 Series Ø 15 mm (.59-in) Can-Stack Stepper Motor Linear Actuators

Delivering force of up to 8 lbs (35N) without compromising long life or cost. Lightweight models can also be micro- stepped for even finer resolution. Bi-directional travel motor.

The world's smallest commercial linear stepper motor

#### Multiple versions available

- Captive
- External Linear
- External Linear with ZBMR Nut

#### Specifications

Opodinoationo						
	Ø 15 mm (,59-in) Motor					
Part No.	Captive	LC1574 -	_ †			
	External Linear	LE1574 -	_ †			
Wiring		Bipo <b>l</b> ar				
Step angle		18°				
Winding Voltage	4 VDC	5 VDC	12 VDC			
Current (RMS)/phase	0.2 A	0.16 A	0.07 A			
Resistance/phase	20 Ω	31 Ω	180 Ω			
Inductance/phase	5.6 mH	8.7 mH	48.8 mH			
Power Consumption		1.6 W				
Rotor Inertia		0.09 gcm <sup>2</sup>				
Insulation Class		Class B (Class F available)				
Weight	LC15 0.49 oz (14 g) LE15 0.39 oz (11 g)					
Insulation Resistance	20 ΜΩ					
Stroke	0.5-in. (12.7 mm)					



Linear Tra	Linear Travel / Step			
inches	mm	Code I.D.		
.00079*	.02	W		
.00098*	.025	AQ		
.00197*	.05	BH		
.00394*	.10	DC		

\*Values truncated

Available Standard Connectors for Series 15000					
Connector	P <b>i</b> N				
Connector	1	2	3	4	
JST PHR-4	Red	White	Green	Black	
Molex 51021-0400	Black	Green	White	Red	

Available Flying Leads				
Length	Order Code I.D. Suffix (add to end on I.D.)			
12 inches (304.8 mm)	<b>-</b> 999			

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

#### Identifying the Can-Stack Number Codes when Ordering

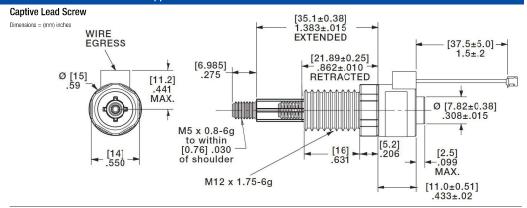
LC	15	7	4	W	04	999
Prefix	Series Number	Style	Coils	Code ID Resolution	Voltage	Suffix
LC = Captive	Designation	<b>7</b> = 18°	4 = Bipolar	Travel/Step	<b>04</b> = 4 VDC	Stroke
LE = External	15 = 15000	Captive	(4 wire)	<b>W</b> = .00079-in (.02)	05 = 5 VDC	Example: -999 = 12-in leads
Linear	(Series numbers			AQ = .00098-in (.025)	12 = 12 VDC	-XXX = Proprietary suffix assigned
	represent approximate			BH = .00197-in (.05)		to a specific customer application.
	diameters of			DC = .00394-in (.10)	Custom V available	The identifier can apply to either
	motor body)				available	a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.





#### ✓ 15000 Series • Can-Stack Stepper Motor Linear Actuators



#### **External Linear** Ø [11.48±0.03] [37.5±5.0] Dimensions = (mm) inches WIRE .452±.001 1.5±.2 EGRESS-M8 x 1-6g to within [1.9] .075 of shoulder Ø [15] [11.2] .441 MAX Ø [7.82±0.38] HOUSING: .308±.015 Ø [1.3] JST P-HR-4 Up to 2.36-in (59.9 mm) standard screw lengths. (or equivalent) CONTACT: Consult factory for longer screws. .099 .099 SPH-002T-PO.5 MAX. [5.1] .200 (or equivalent) [23.9] .941 [11.0±0.51] .433±.02

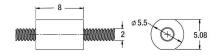
#### MICRO Series

Dimensions = (mm) inches

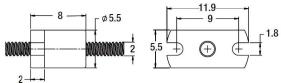
Standard nut styles. Consult the factory for custom solutions.

MICRO Series Nut Styles					
Part No.	BFW Nut Style	Dynamic Load Ibs (Kg)	Drag Torque oz-in (NM)		
BFWB	Barrel Mount	10 (4.5)	Free Wheeling		
BFWR	Rectangular Flange	10 (4,5)	riee wheeling		

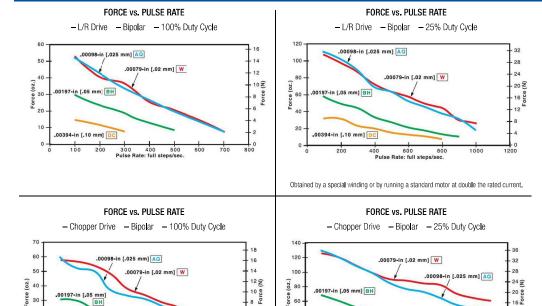
#### Barrel Nut Style



#### Rectangular Nut Style



#### ■ 15000 Series • Can-Stack Stepper Motor Linear Actuators



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

40

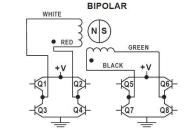
Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

### 15000 Series • Can-Stack Stepper Motor Linear Actuators Wiring & Stepping Sequence

#### Can-Stacks: Wiring

20

.00394-in [-10 mm]



100 600 800 Pulse Rate: full steps/sec.

### Can-Stacks: Stepping Sequence

.00394-in [.10 mm]

	Bipolar	Q2 <del>-</del> Q3	Q1-Q4	Q6 <b>-</b> Q7	Q5-Q8	
叉	Step					<b></b>
EXTEND	1	ON	OFF	ON	OFF	
CW-	2	0FF	ON	ON	OFF	MOO.
1	3	OFF	ON	OFF	ON	RETRACT
٧	4	ON	0FF	OFF	ON	8
	1	ON	OFF	ON	OFF	

400 600 80 Pulse Rate: full steps/sec.

800

Note: Half stepping is accomplished by inserting an off state between transitioning phases.





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12



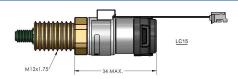
#### NEW! 15000 Series E16 Encoder

15000 Series E16 optical encoder is designed to provide A, B and Index digital quadrature signals for high volume, restricted space applications.

- Resolutions from 250/256 to 4000/4096
- · Single-ended only
- . Low power consumption, 5V @ 26mA max

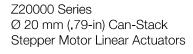
Assembly Options:

- Detachable cable





Pin #	Description
1	Ground
2	Index
3	A channel
4	+5VDC power
5	B channel



Utilizing rare earth (neodymium) magnets, the Z-Series Linear Actuators consistently deliver exceptional performance at an economical price. Also available in a special "earless" configuration without a mounting flange, which is ideal for space constrained applications.

#### Economical motors for high volume applications

#### Multiple versions available

- Captive
- Non-Captive
- External Linear

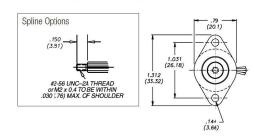


#### Specifications

	Ø 20 mm (.79-in) Z-Series N	Motor					
	Captive	Z2054 – – †					
Part No.	Non-Captive	Z2084 – – †					
	External Linear*	Z2054 – – 9 <sup>†*</sup>					
Wiring	В	Bipolar   15°   12 VDC   12 VDC   250 mA   100 mA					
Step angle		15°					
Winding Voltage	5 VDC	12 VDC					
Current (RMS)/phase	250 mA	100 mA					
Resistance/phase	$20\Omega$	118 Ω					
Inductance/phase	5.4 mH	27 mH					
Power Consumption	2	2.5 W					
Rotor Inertia	1.1	3 gcm <sup>2</sup>					
Insulation Class	C <b>l</b> ass B						
Weight	.85 0	z. (24.1 g)					
Insulation Resistance	21	0 MΩ					

\*\*Part numbering information\_on page 168.

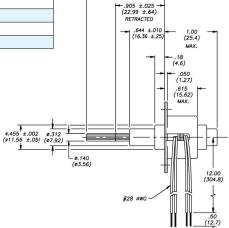
\*\*When ordering Z-Series External Linear motors, add -900 to end of the Part Number.



Linear Tra 15° Ste	Order Code I.D.		
inches	mm	OOGC I.D.	
0.001	0.0254	1	
0.002	0.051	2	
0.004	0.102	4	

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

(36.78) EXTENDED







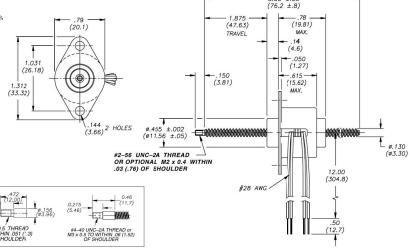
#### Z20000 Series • Can-Stack Stepper Motor Linear Actuators

#### Non-Captive Lead Screw

Dimensions = (mm) inches

Up to 6-in (152 mm) standard screw lengths. Longer screw lengths are available.

> **Optional Adapters** Adapters

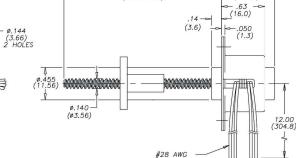


### **External Linear**

Dimensions = (mm) inches Up to 6-in (152 mm) standard screw lengths.

- .79 <del>-</del> (20.1) Longer screw lengths are available. 1.312 (33.32) 1.031

(26.18)



4 LEAD WIRES

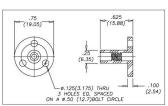
3.000±.030

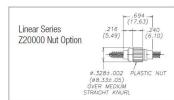
(76.20±.762)

(19.81)

.50 (12.7)

3.00 ±.03





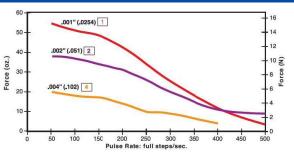


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#### Z20000 Series • Can-Stack Stepper Motor Linear Actuators

#### FORCE vs. PULSE RATE

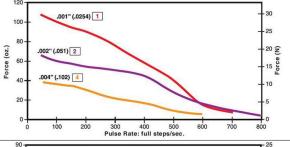
- L/R Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

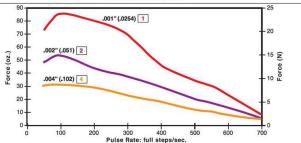
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current,



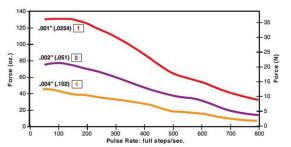
#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

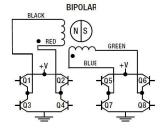
Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

#### Identifying the Can-Stack Number Codes when Ordering

Z	20	5	4	2	05	900
Prefix Z = Series Code	Series Number Designation 20 = 20000 (Series numbers represent approximate diameters of motor body)	Style  5 = 15° Captive or External (use -900 Suffix for External version)  8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 4 = .004-in (.102)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -900 used to code Z-Series external linear  -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (+) as shown above. For assistance call our Engineering Team at 203 756 7441.

#### Can-Stacks: Wiring



#### Can-Stacks: Stepping Sequence

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8	Ì
異	Step					<b>A</b>
EXTEND CW	1	ON	0FF	ON	OFF	
CW-	2	OFF	ON	ON	OFF	CCW
	3	OFF	ON	OFF	ON	RETRACT
•	4	ON	0FF	0FF	ON	Æ
	1	ON	OFF	ON	OFF	

#### ■ Can-Stack Stepper Motor Linear Actuators Options

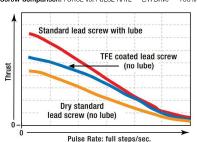
#### TFE Coated Lead Screws for applications that require a permanent, dry lubricant

Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a "dry" stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external

Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.

Lead Screw Comparison: FORCE vs. PULSE RATE - L/R Drive - 100% Duty Cycle





	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8	
Ξ.	Step					<b>A</b>
EXTEND	1	ON	0FF	ON	OFF	
CW-	2	OFF	ON	ON	OFF	SS
	3	OFF	ON	OFF	ON	RETRACT CCW
•	4	ON	0FF	0FF	ON	뜐
	1	ON	OFF	ON	OFF	

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

#### End of Stroke Proximity Sensor incorporates a hall effect device, activated by a rare earth magnet embedded in the end of the internal screw

Can-Stack Stepper Motor Linear Actuators Options Specially Engineered Can-Stack Linear Actuators

Stepping motors specially designed for high temperature environments. Materials meeting class F temperature ratings are used in construction. Specialized components include high temperature bobbins, coils, lead wires,

Home Position Switch monitors movements more precisely

Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions. Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available. Activation force of 10 oz (2.78 N) required therefore may not be appropriate for

When ordering motors with the home position switch, the part number should be

for greater control and improved quality control

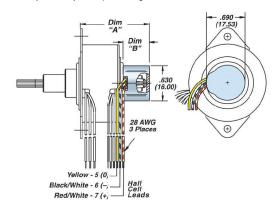
for high temperature applications

Jubricant and adhesives.

smaller can-stack actuators.

preceded by an "S".

Compact profile of the sensor allows for installation in limited space applications. Virtually unlimited cycle life. Special cabling and connectors available.



30		-8
25		
⊋ 20	.001 (.0254) 1	+
20 (ozin.) 15 15	.002 (.051)	
Ign 10	2	
5		-2
-	.004 (.102) 4	

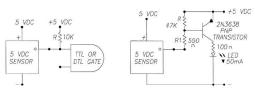


200 300 400 500

Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 milliohms typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	1

#### Supply Voltage (VDC) 3.8 min. to 24 max. Current Consumption 10 mA max. Output Voltage (operated) 0.15 typ., 0.40 max. Sinking 20 mA max. Output Current 20 mA max. Output Leakage Current 10μA max. @ Vout = 24 VDC; Vcc = 24 VDC (released) .05 µs typ., 1.5 µs max. @ Vcc = 12 V, RL = 1.6 KOhm Output Switching 10 to 90%

.15 us tvp., 1.5 us max, @ CL = 20 pF - 40 to +150°C



NOTE: Sensor is category 2 ESD sensitive per DOD-STD-1686A. Assembly operations should be performed at workstations with conductive tons and operators orgunded







Fall, 90 to 10%

Temperature

Specifications



#### Z26000 Series • Can-Stack Stepper Motor Linear Actuators

Z26000 Series Ø 26 mm (1-in) Can-Stack Stepper Motor Linear Actuators

#### Designed to accommodate high volume applications

Z26000 Series motors utilize rare earth (neodymium) magnets. Also, available in a special "earless" configuration without a mounting flange. All units are built with durable dual ball bearings.

#### Multiple versions available

- Captive - Non-Captive - External Linear

NOW AVAILABLE! Shorter motor body option available (see page 174)



#### Specifications

opoundations										
				Ø 26 mm (1-in)	Z-Series Motor					
	Captive	Z2644 –		Z2654 –		Z2646 –		Z2656 –		
Part No.	Non-Captive	Z2634 -	+	Z2684 -		Z2636 -	t	Z2686 -	t	
	External Linear*	Z2644 –	<b>-</b> 9 ***	Z2654 -	-9 t"	Z2646 –	-9 t''	Z2656 -	<b>-</b> 9 ***	
	Wiring		Bip	olar			Unip	polar*		
	Step angle	7.	5°	15	5°	7.5°		1:	ō°	
Wir	nding Voltage	5 VDC	12 VDC	5 VDC	12 VDC	5 VDC	12 VDC	5 VDC	12 VDC	
Curre	nt (RMS)/phase	340 mA	140 mA	340 mA	140 mA	340 mA	140 mA	340 mA	140 mA	
Resi	istance/phase	14.7 Ω	84 Ω	14.7 Ω	84 Ω	14.7 Ω	84 Ω	14.7 Ω	84 Ω	
Indu	ictance/phase	8.5 mH	55 mH	6.7 mH	44 mH	4.3 mH	24 mH	3.4 mH	19 mH	
Powe	er Consumption				3.4	ł W				
R	otor Inertia				1.4	gcm²				
Ins	ulation Class		Class B							
	Weight		1.2 oz (34 g)							
Insula	tion Resistance				20	MΩ				

\*Part numbering information\* on page 4. \*Unipolar drive gives approximately 40% less thrust compared to bipolar drive. \*\* When ordering Z-Series External Linear motors, add +900 to end of the Part Number.

	Linear Travel / Step 15° Step Angle						
step	inches	inches mm					
7.5° Ang <b>l</b> e	0.0005	0.013	3				
	0.001	0.0254	1				
ringio	0.002	0.051	2				
	0.00164	0.04166	AS				
15° Ang <b>l</b> e	0.002	0.051	2				
raigio	0.004	0.102	4				

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).



Captive Extended

Captive Extended

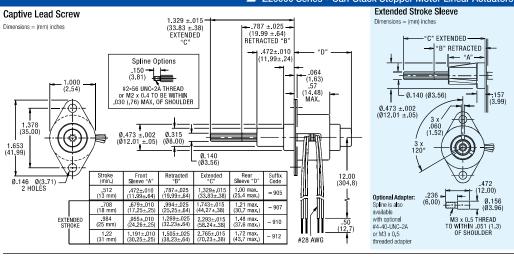


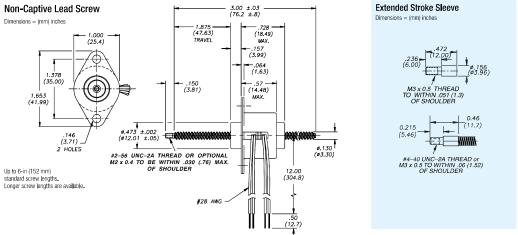


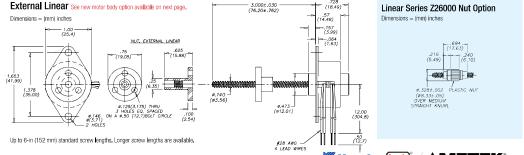
#### www.haydonkerkpittman.com

Captive Extended

#### Z26000 Series • Can-Stack Stepper Motor Linear Actuators







### Z26000 Series • Can-Stack Stepper Motor Linear Actuators

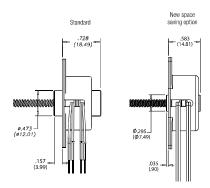


#### NOW AVAILABLE! Shorter External Linear Option

#### Designed to accommodate applications with space limitations

The Z26000 series now offers both the .728 and .583 motor body lengths with all existing Z26 motor advantages, including cost competitiveness and availability of customizations like rare earth magnets and earless options.

When ordering, the shorter motor option can be referenced using the last three suffix digits (-XXX).

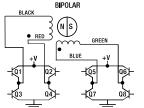


#### Identifying the Can-Stack Number Codes when Ordering

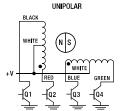
Z	26	4	4	2	05	900
Prefix Z = Series Code	Series Number Designation 26 = 26000 (Series numbers represent approximate diameters of motor body)	Style 3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External version) 5 = 15° Captive or External (use "E" or "K" Prefix for External version 8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102) AS = .04166-in (.00164)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: —900 used to code Z-Series external linear —XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

#### Can-Stacks: Wiring



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#### Can-Stacks: Stepping Sequence

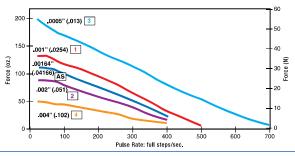
Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8	١.
Step					
1	ON	0FF	ON	OFF	3
2	OFF	ON	ON	OFF	//\J
3	0FF	ON	OFF	ON	RETRACT
4	ON	OFF	OFF	ON	Ĭ
1	ON	0FF	ON	OFF	] "
	Step 1	Step 1 ON 2 OFF 3 OFF 4 ON	Step  1	Step     1	Step       ON

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

### Z26000 Series • Can-Stack Stepper Motor Linear Actuators

#### FORCE vs. PULSE RATE

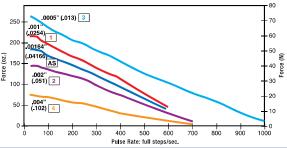
- L/R Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

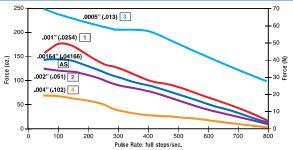
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



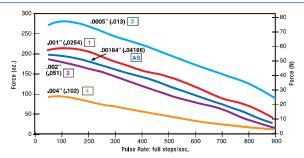
#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.





#### ✓ 46000 Series • Can-Stack Stepper Motor Linear Actuators

46000 Series Ø 46 mm (1.8-in) Can-Stack Stepper Motor Linear Actuators

Heavy-duty power, versatility and high output force

#### Multiple versions available

- Captive
- Non-Captive
- External Linear



#### Specifications

Оростоиной									
	Ø 46 mm (1.8-in) Motor								
	Captive	4644 –		4654 -		4646 –	- 1	4656 -	†
Part No.	Non-Captive	4634 –		4684 –	t	4636 -	†	4686 -	t
	External Linear	E4644 -	†	E4654 -	†	E4646 -		E4656 -	_ †
Wiring		Bipolar			Unipolar*				
Step angle		7.	5°	15°		7.5°		15°	
Wir	nding Voltage	5 VDC	12 VDC	5 VDC	12 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Curre	nt (RMS)/phase	1.0 A	41 A	1.0 A	.41 A	1.0 A	.41 A	1.0 A	.41 A
Resi	istance/phase	5 Ω	29 Ω	5 Ω	29 Ω	5 Ω	29 Ω	5 Ω	29 Ω
Indu	ıctance/phase	9 mH	52 mH	7.1 mH	39 mH	4.5 mH	26 mH	3.5 mH	20 mH
Powe	Power Consumption 10 W								
Rotor Inertia		25.0 gcm²							
Ins	Insulation Class B Class B								
	Weight 9.0 oz (255 g)								
Insula	tion Resistance	20 ΜΩ							

\*Part numbering information on page 177. \*Unipolar drive gives approximately 30% less thrust than bipolar drive.

Lin	Order Code I.D.				
step	inches	Oouc I.D.			
	0.0005	0.013	3		
	0.001	0.0254	1		
7.5° Angle	0.002	0.051	2		
ruigio	0.004	0.102	4		
	0.008	0.203	8		
	0.004	0.102	4		
15° Ang <b>l</b> e	0.008	0.203	8		
, anglo	0.016	0.406	G		

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted. Standard motors are Class B rated for maximum temperature of 130° C (266° F).

Other 46000 Series styles available:

- TFE lead screw
- · High temperature option

NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

## 192 **Haydon** kerk



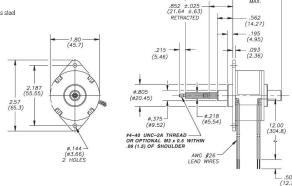
## ✓ 46000 Series • Can-Stack Stepper Motor Linear Actuators 1.802 ±.015 (45.77 ±.38) EXTENDED

(45.08)

#### Captive Lead Screw

Dimensions = (mm) inches

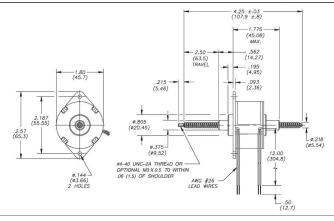
Pinion shafts available as electroless nickel plated brass (standard) or stainless steel (optional) threaded end.



#### Non-Captive Lead Screw

Dimensions = (mm) inches

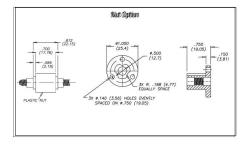
Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.

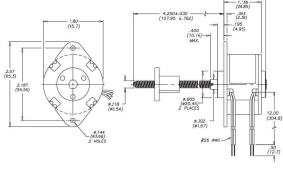


#### **External Linear**

Dimensions = (mm) inches

Up to 10-in (254 mm) standard screw lengths. Longer screw lengths are available.







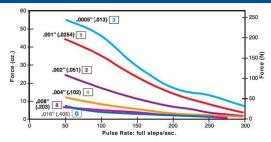


(32.'8) MAX

#### ✓ 46000 Series • Can-Stack Stepper Motor Linear Actuators

#### FORCE vs. PULSE RATE

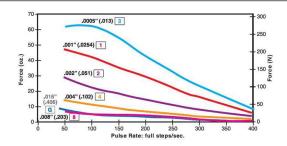
- L/R Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

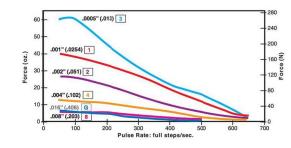
- L/R Drive
- Bipolar
- 25% Duty Cycle

Obtained by a special winding or by running a standard motor at double the rated current.



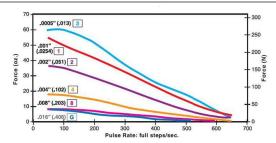
#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 100% Duty Cycle



#### FORCE vs. PULSE RATE

- Chopper Drive
- Bipolar
- 25% Duty Cycle



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply. Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

## 194 **Haydon** kerk



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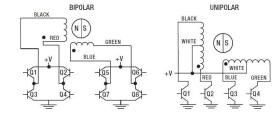
#### ✓ 46000 Series • Can-Stack Stepper Motor Linear Actuators

#### Identifying the Can-Stack Number Codes when Ordering

E	46	4	4	3	05	900
Prefix (include only when using the following)  E = External K = External with 40° thread form S = Home Position Switch R = Rare Earth Magnet	Series Number Designation 46 = 46000 (Series numbers represent approximate diameters of motor body)	Style 3 = 7.5° Non-Captive 4 = 7.5° Captive or External (use "E" or "K" Prefix for External version) 5 = 15° Captive or External (use "E" or "K" Prefix for External version 8 = 15° Non-Captive	Coils 4 = Bipolar (4 wire) 6 = Unipolar (6 wire)	Code ID Resolution Travel/Step 1 = .001-in (.0254) 2 = .0002-in (.051) 3 = .0005-in (.013) 4 = .004-in (.102) 8 = .0008-in (.203) G = .016-in (.406)	Voltage 05 = 5 VDC 12 = 12 VDC Custom V available	Suffix Stroke Example: -900= external linear with grease and llanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (+) as shown above. For assistance call our Engineering Team at 203 756 7441.

#### Can-Stacks: Wiring



#### Can-Stacks: Stepping Sequence

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8	
$\nabla$	Step					<b></b>
EXTEND	1	ON	OFF	ON	0FF	
CW-	2	OFF	ON	ON	OFF	CCW
1	3	0FF	ON	OFF	ON	RETRACT
٧	4	ON	OFF	OFF	ON	E
	1	ON	OFF	ON	0FF	

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Can-Stack Stepper Motor Linear Actuators Options

#### TFE Coated Lead Screws for applications that require a permanent, dry lubricant

Ideal for applications where conventional oils and greases cannot be used for lead screw lubrication.

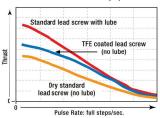
Non-lubricated TFE Coated Lead Screw provides improved performance in both life and thrust as compared to a "dry" stainless steel lead screw. TFE can be applied to a wide variety of lead screw pitches. Available captive, non-captive and external linear.

Typical applications: where contamination from grease or lubricants must be avoided; silicon wafer handling, clean rooms, medical equipment or laboratory instrumentation.



#### Lead Screw Comparison: FORCE vs. PULSE RATE

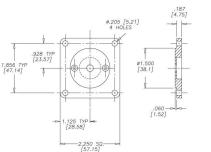
- L/R Drive - 100% Duty Cycle



#### Specially engineered can-stack linear actuators for high temperature applications

Special materials meet class F temperature ratings are used in construction. Specialized components include high temperature bobbins, coils, lead wires, lubricant and adhesives.

# **NEMA Flange** Assembly option available for applications that require a Size 23 mount.



#### Home Position Switch monitors movements more precisely for greater control and improved quality control

Miniature electronic home position switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions. Depending on your preference, contacts can be normally open or normally closed. The contact closure is repeatable to within one step position, identifying linear movements as low as 0.0005-in (0.0013 cm) per step. Multiple contact switches are also available.

Activation force of 10 oz (2.78 N) required therefore may not be appropriate for smaller can-stack actuators.

When ordering motors with the home position switch, the part number should be preceded by an "S".

Specifications	
Contact Ratings (Standard)	1.00 AMP @ 120 VAC 1.00 AMP @ 28 VDC
Operating Temperature	-30°C to +55°C (-22°F to 131°F)
Electrical Life	< 20 milliohms typ. initial at 2 - 4 V DC, 100 mA Tested to 60,000 make-and-break cycles at full load
Schematic	1